

Projet ANR- 09-NANO-008-AXOC

AXOC: Advanced X-ray Optics Components coupled high accuracy mechanics for X-ray nano-focusing

01/12/2009- 31/05/2013

Project coordinator: A. Somogyi, Soleil

Journées Nationales Nanosciences et
Nanotechnologies 2012



AXOC: partners

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AXOC: project goals

Development of a state-of-the-art scanning hard X-ray nanoprobe including:

- nano-focusing Kirckpatrick-Baez mirror-system
 - mirror fabrication
 - mechanics
- a high precision sample stage

Development of **optical and at wavelength metrology** techniques adapted to the characterization of very high optical quality mirrors

adapted to the Nanoscopium beamline of Synchrotron Soleil

Nanoscopium: Scanning hard X-ray imaging beamline at Synchrotron Soleil (St Aubin)



155 long nanoprobe beamline, aiming down to 30 nm spatial resolution

Exploitation of beam coherence for focusing and contrast formation

Diffraction limited focusing

Multimodal and multi-technique imaging
Chemical and structural information

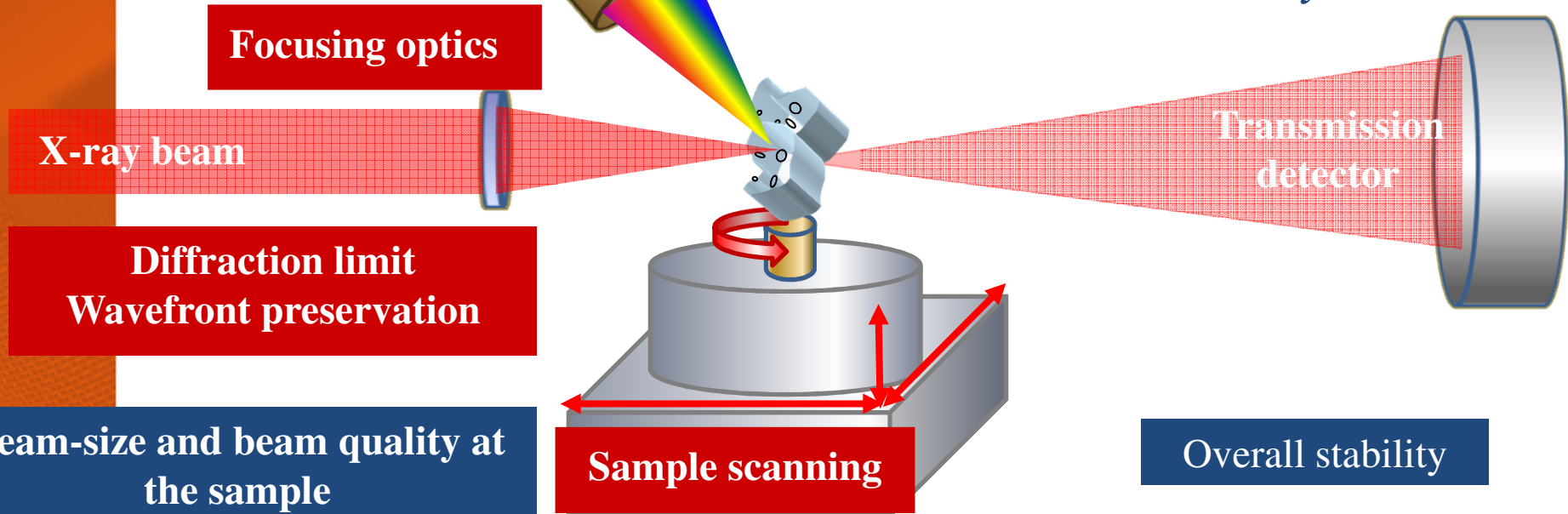


Responsible: A. Somogyi

Scanning hard X-ray nano-imaging

SXRF elemental imaging
XANES chemical information

Diff. phase contrast imaging
Coherent scattering imaging
Structural information,
electron density distribution



Beam-size and beam quality at the sample

Sample stage: Precision XYZ Θ
~5-10 nm resolution (encoder, feedback)

AXOC-project

Resolution, performance

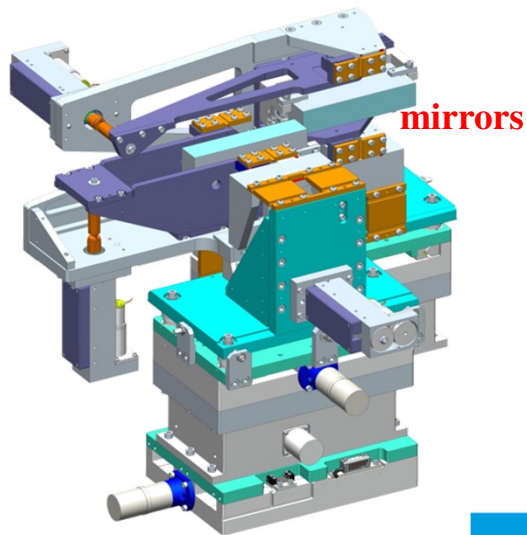
Deliverables of the AXOC project

Focusing optics: Kirkpatrick-Baez mirror system

Diffraction-limited focusing and coherence based applications: high optical mirror quality, **Mirror conception (Task1, Soleil)**

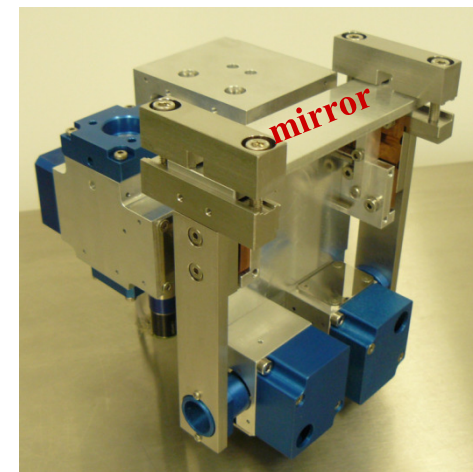
Two alternative principles

Monolithic, elliptically shaped Si mirrors, deterministic polishing (Task3, SESO)



High stability, high precision mirror positioning (Task2, ISP)

Bent Si mirrors, lateral shape optimisation, deterministic polishing (Task3, SESO)



Adaptation of the existing bending system (ISP) constructed by FEASO RTRA Project (2007)

Deliverables of the AXOC project

Development of adapted mirror metrology tools (Task5)

Surface correction of flat SiO₂ mirrors by det. deposition: high quality metrology standard for intercomparison (Task4, LMA)



Vertical translation stage with nanometer precision and mm travel range (Task2, ISP)

Task1: Mirror conception

The conception of 3 mirror-pairs has been finished

Total reflection KB mirror systems for Nanoscopium with Elliptical mirror shape: by two alternative principles

- **Monolithic, elliptically shaped Si mirrors**
- **Flat Si mirrors, lateral shape optimisation, elliptical shape by bending**

Surface finishing by deterministic polishing (SESO, Task3)

- **Flat SiO₂ mirrors:** for high quality metrology standard
- Surface correction by deterministic deposition (LMA, Task4)

Example: Flat Si mirrors, lateral shape optimisation, elliptical shape by bending

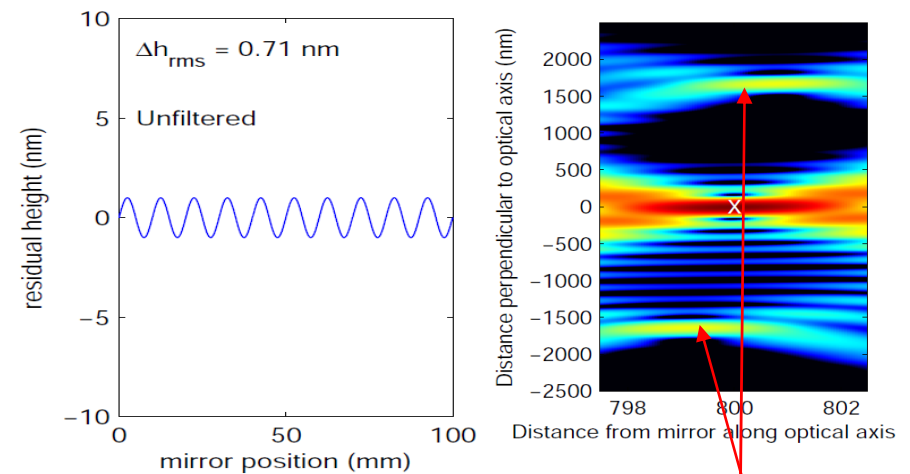
Working strategy :

- High precision bending mechanical system (ISP)
- Two high optical quality flat mirrors with lateral shape optimization for the required working conditions (Thalès-SESO, SOLEIL)

Required characteristics by wave-optical calculations (SOLEIL)

Figure errors must be below 0.75 nm-rms to achieve more than 0.8 Strehl ratio over 5-20 keV energy range.

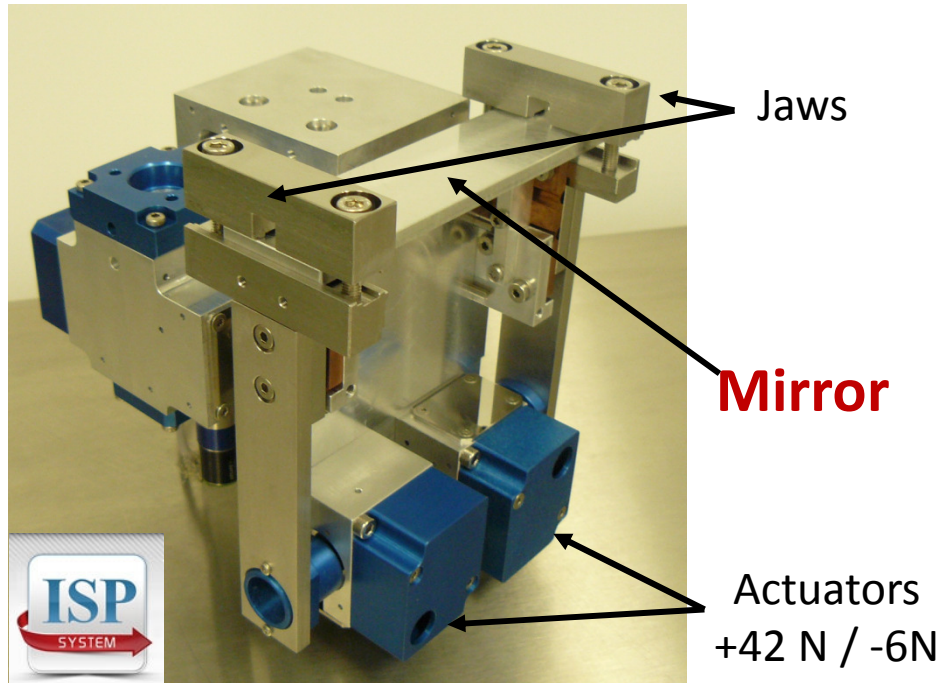
The amplitude of periodic errors, particularly with spatial period above a few mm, must be minimised.



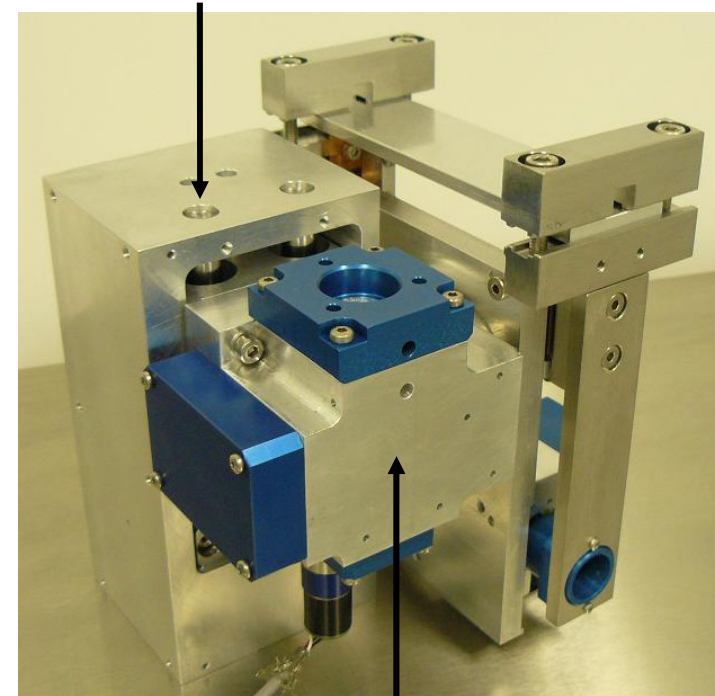
10 mm spatial period \rightarrow 10% I_{max} side-lobes
P-V = 1 nm

FEASO RTRA Project (2007)

Thematics: « Instrumentation à ses limites » & « Lumière extrême »



Translation Stage (+/- 3 mm)



Rotation Stage (+/- 30 mrad)

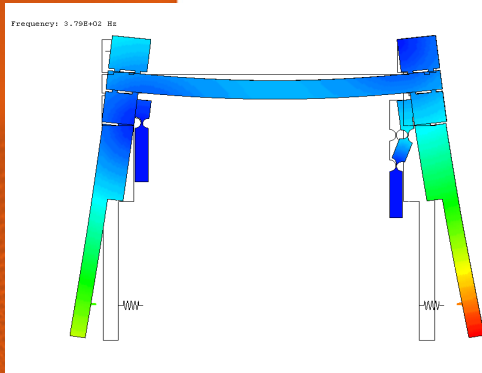


2 actuators bending mechanical system
Large range of elliptical profiles achievable
Dynamic Range : $R = 800 \text{ m} \rightarrow R = 20 \text{ m}$
Sag up to $40 \text{ }\mu\text{m}$ over 80 mm useful length

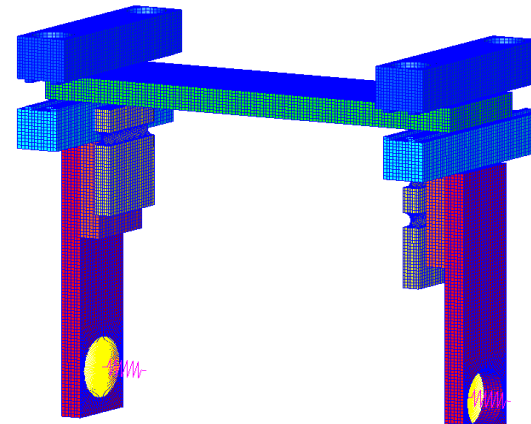
Historical

Finite Element Analysis Model (IDEAS) :

Solid elements : 4 mm mesh
Mirror surface : 1 mm mesh
(allows to retrieve the local slopes
with 1 mm spatial resolution)



Bender ReDesign



166 465 nodes
141 104 elements

In test

**Modal analysis shows a first
vibration mode at 379 Hz**

Mirror width profile optimisation

Elastic Beam Theory approximation

FEA Influence Functions and Interaction Matrix based Optimisation

Lateral profiling and surface finishing in progress (SESO)



Task2: Construction of positioning systems (mechanics, motion control)



High precision, high stability positioning system for monolithic, elliptically shaped Si mirrors

Technical specifications, tolerances, stability criteria (Soleil): based on wavefront propagation calculations

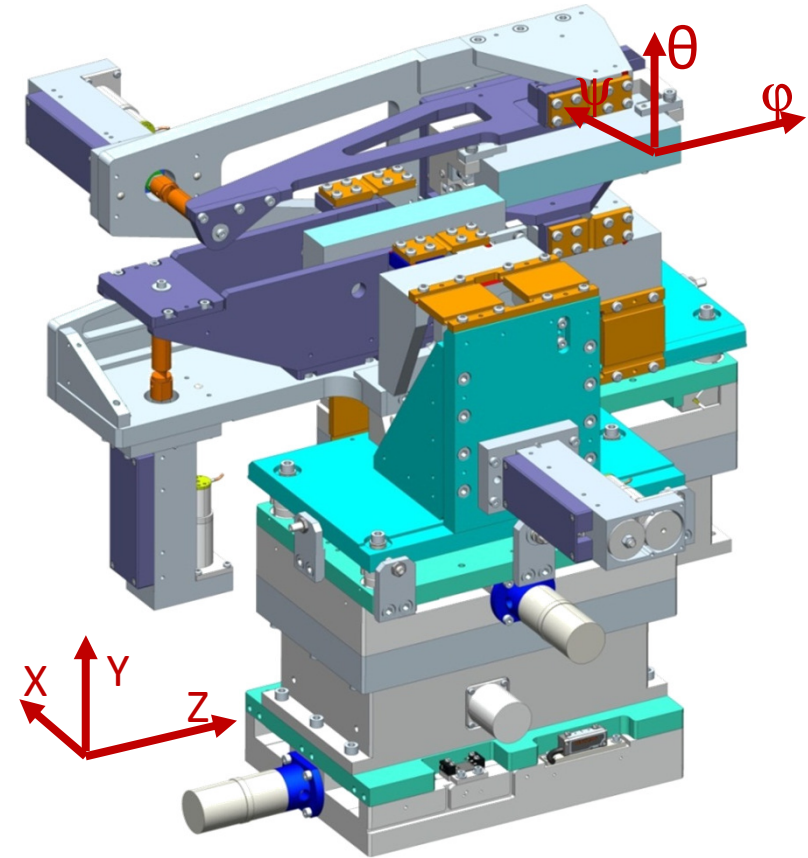
Demanded mirror motions :

M1 mirror

- 3 motorised translation: X1, Y, Z1
- 2 motorised rotations: θ_1 and ϕ_1
- 1 rotation manuelle : ψ_1

M2 mirror:

- 2 translations motorisées : X2, Y2
- 1 rotation motorisée : θ_2
- 2 rotations manuelles : ϕ_2 et ψ_2



2 independent, closely embeded mechanics

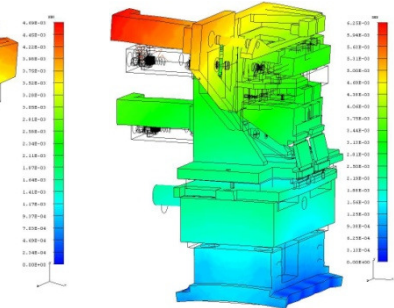
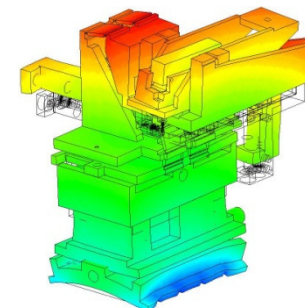
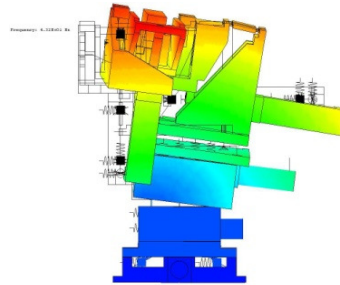
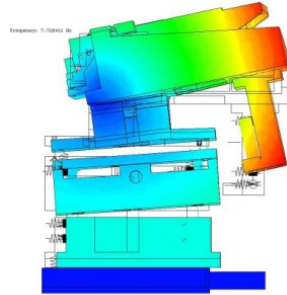
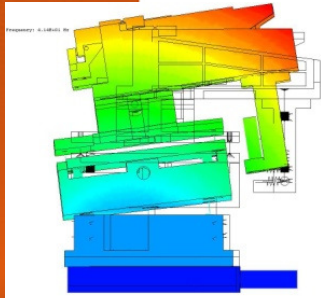
Critical motions for mirror performance		Range	Resolution	Precision
θ_2, θ_2	Pitch	-0.1°-0.2°	0.15 μrad	0.5 μrad
ϕ_1	Roll, perpendicularity	+/- 100μrad	5μrad	10μrad



Working strategy :

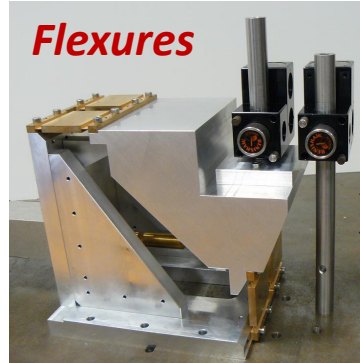
*Finite element calculations and dimensioning,
calculation of the first eigen-frequencies ($\geq 40\text{Hz}$)*

*Thermo-mechanical analysis
of the ensemble*

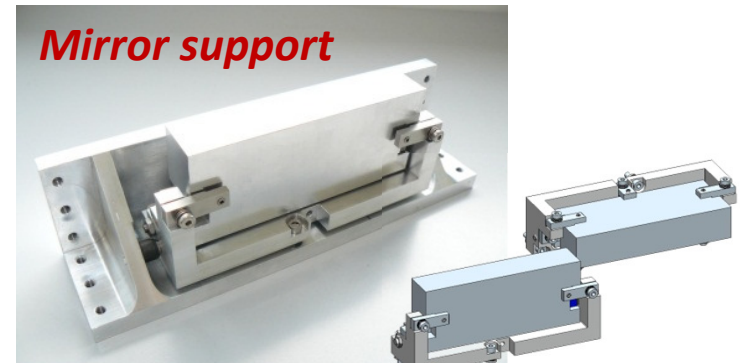


Prototypes

*Validation of the dimensioning
of the critical elements*



Flexures



Mirror support

Pitch: $0.15 \mu\text{rad}$ resolution distortion-free mirror fixation
 $0.5 \mu\text{rad}$ precision



*Fabrication of the components of the validated final
design*

**Assembling tests: 2012 Nov-Dec
Delivery to Soleil 2013 Febr**

Diapositive 14

HJ11

modifier le bandeau à gauche pour différencier des présentation officielle ANR?

HACCOUN Julien; 25/07/2012



Vertical sample positioning stage

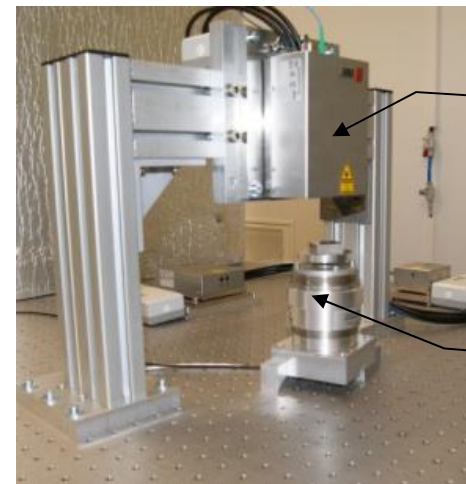
Technical specifications, tolerances, stability criteria (Soleil)

Travel range: 1-2 mm

Resolution: 5 nm

Scanning modes:

- Continuous fast (1 mm/s) « fly scan »
- Precision step scan, with ~5 nm resolution



3 axis
interferometer

prototype

Working principle:

- high precision translation stage (linear motor, flexure based guidance) with load compensation mechanism
- dedicated electronics for motion control

Challenges:

- Obtaining electronic noise levels compatible with 5 nm resolution & mm travel range
- « Flyscan » mode

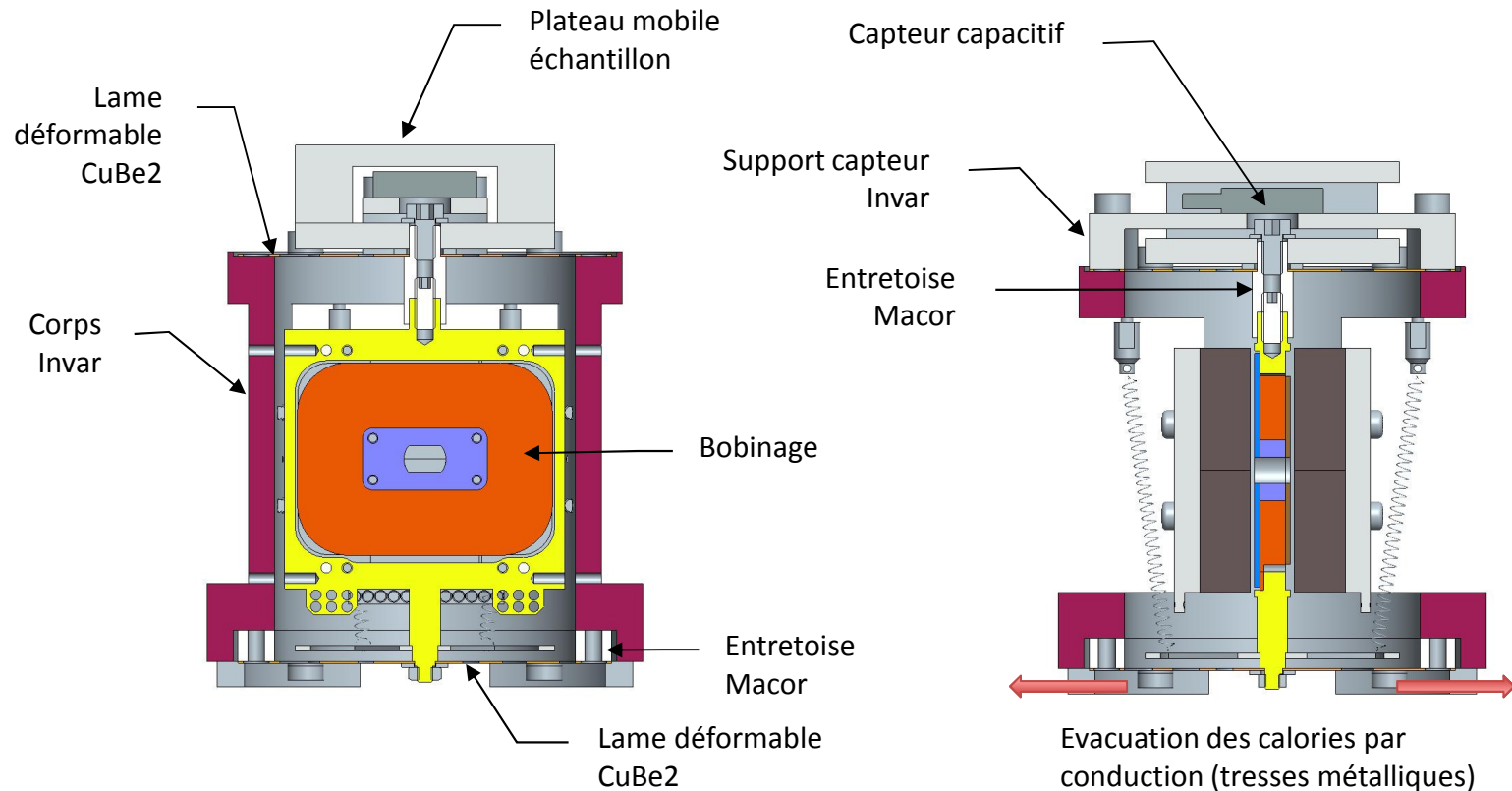
HJ7



Sample positioning

→ Optimization: minimizing the heat transfer to the sample

Take into account and correct for the differential dilatation in the closed loop feedback



Dépôt de brevet (ISP):

→ Actuateur linéaire sans contact à guidage flexible et application à une table de déplacement

Diapositive 16

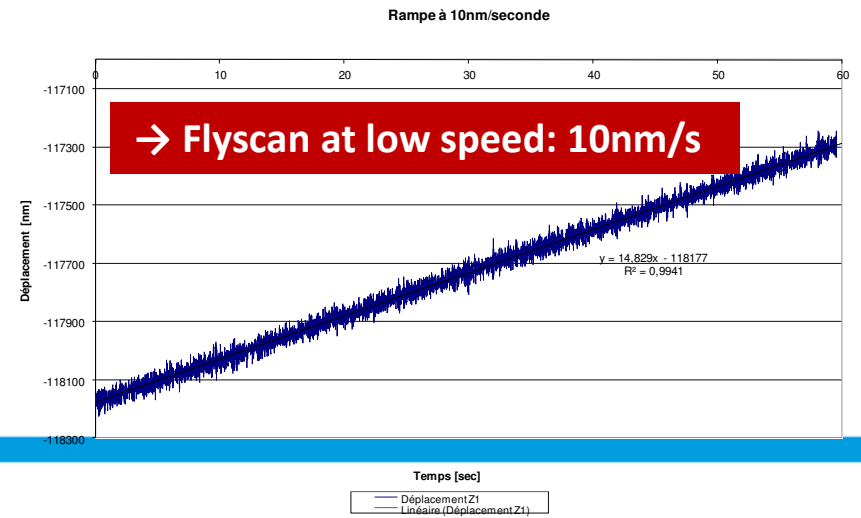
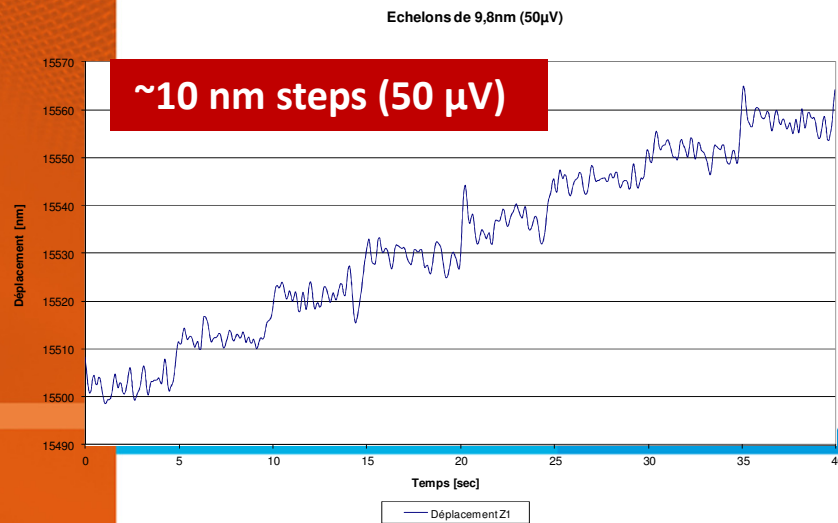
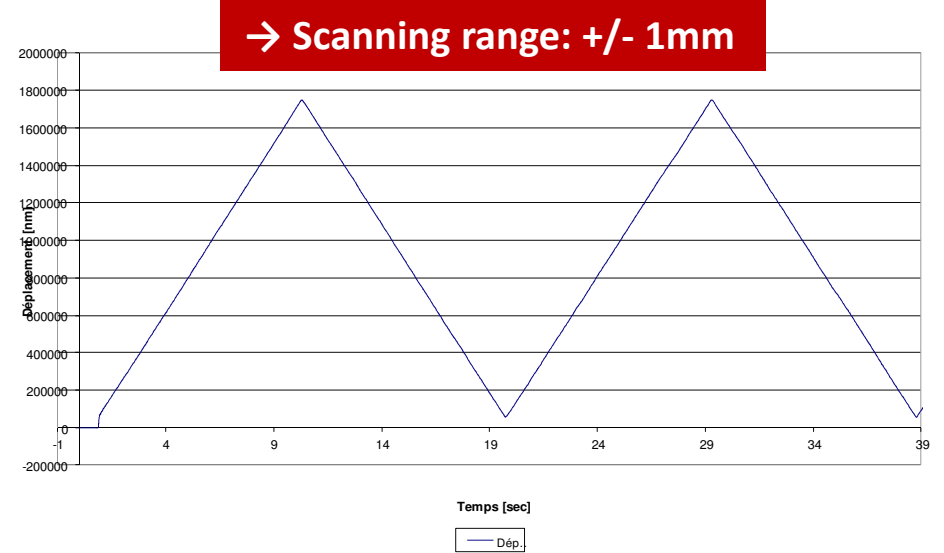
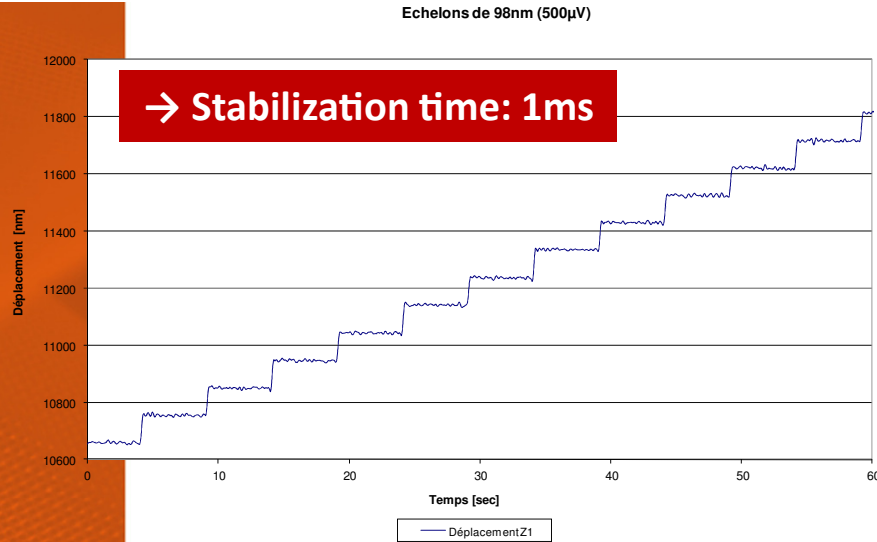
HJ7

modifier le bandeau à gauche pour différencier des présentation officielle ANR?

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Sample positioning

→ **Validation of the electronic control and the closed loop feedback**



→ Resolution <1nm with 24 bits control electronics

Diapositive 17

HJ8

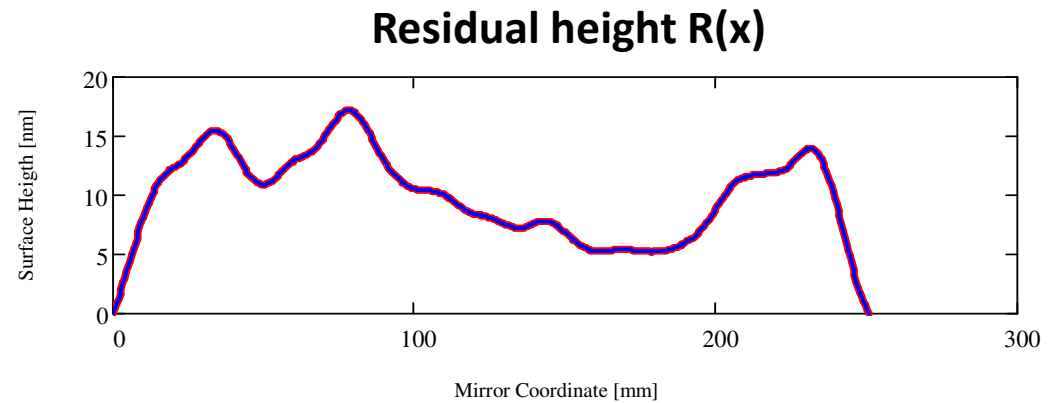
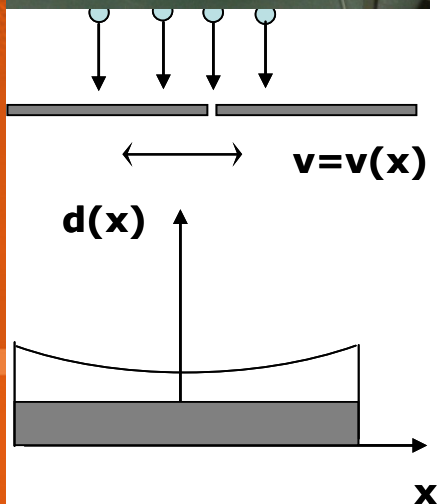
modifier le bandeau à gauche pour différencier des présentation officielle ANR?

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Task 3: Mirror fabrication by deterministic ion-beam polishing (IBP)

SESO : Experimental facility (mirror lengths < 1.5 m): thin film coating & IBP



Aim: correction of the artifacts of standard polishing

Local correction of less 1 nm in height can be reliably applied

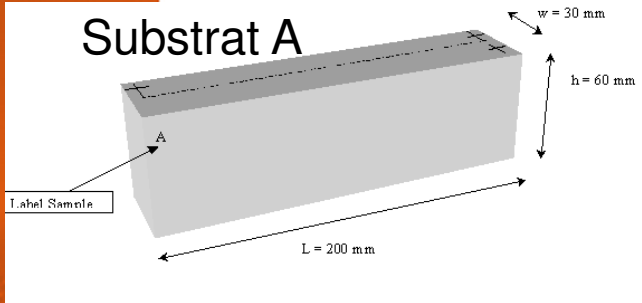
IBP Steps

1. **Measure height profile $P(x)$**
2. **Ellipse equation (goal), $E(x)$**
3. **Evaluation of residual height $R(x)$**
 $\rightarrow R(L)=R(0)=0$
4. **Calculation $v(x)$**

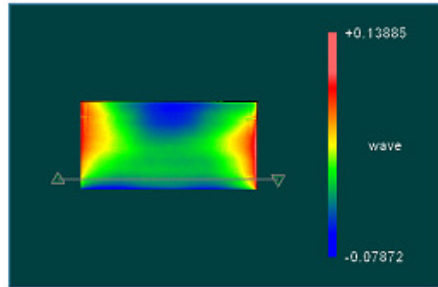
Mirror fabrication by IBP (SES0)

Results: surface finishing is in progress

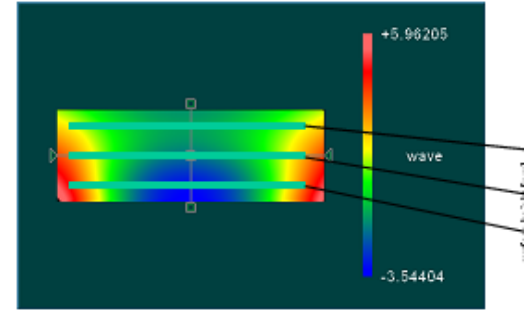
Si substrates for monolithic elliptically shaped mirrors



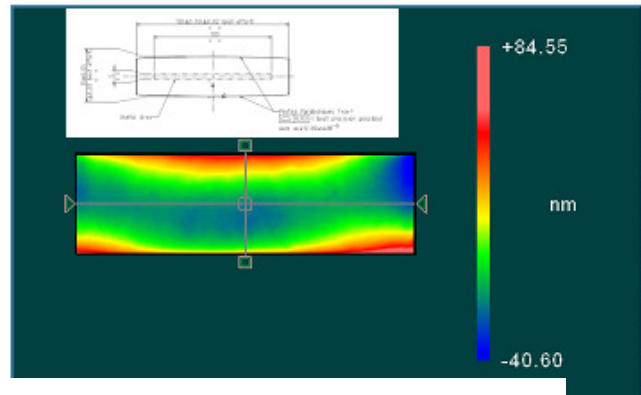
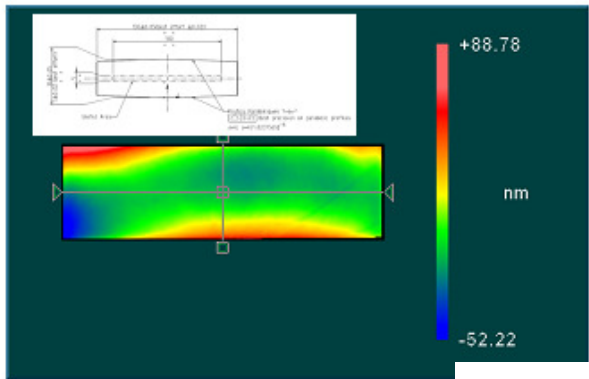
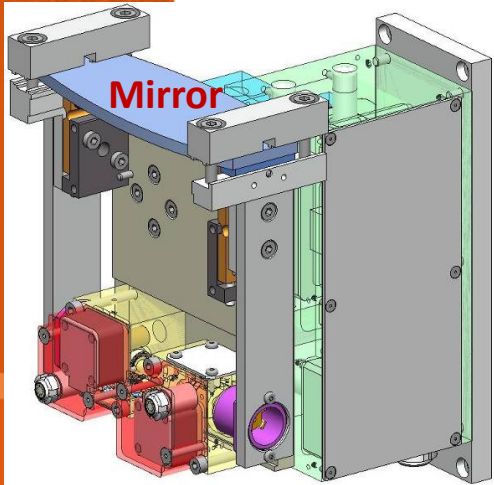
Nano-MRX (before IBP)



Nano-MRX(after IBP)



Si substrates for flat, torpedo shaped mirrors



Before torpedo cutting

CNC Cutting of TORPEDO shapes (in progress) (+/- 30 μm accuracy)



Task 4: Surface finishing by deterministic deposition

Working strategy

Definition of mirror characteristics (SOLEIL)



Polishing of SiO₂ substrates & visible metrology & fiducial markers for comparative metrology and det. deposition (SESO)



Comparative métrologie before det. deposition (SESO, SOLEIL, LMA)



Deterministic deposition (LMA)



Comparative métrologie after det. Deposition (SESO, SOLEIL, LMA)

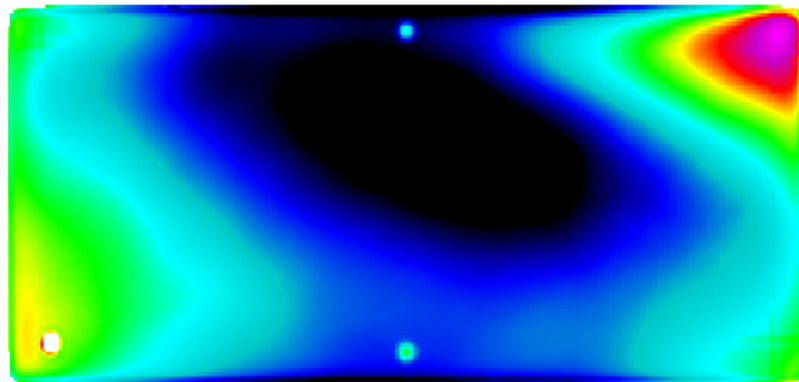


Validation

Starting SiO₂ substrates (polished by SESO)

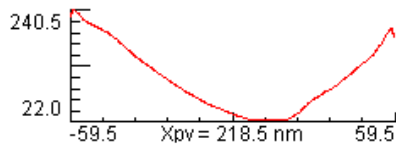
Substrat A

Shape error P to V: 218 nm



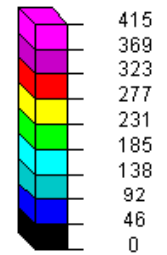
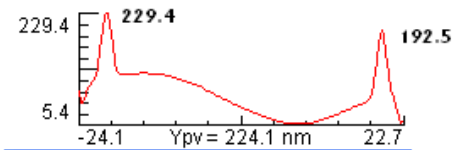
Coupe sur l'axe X

Fermer Copier Options Sauver



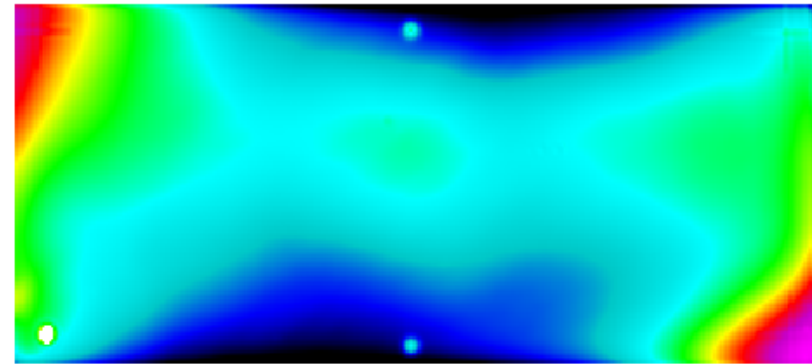
Coupe sur l'axe Y

Fermer Copier Options Sauver



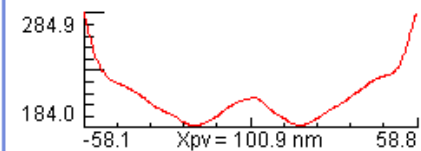
Substrat B

Shape error P to V: 76 nm



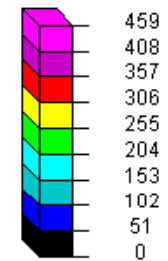
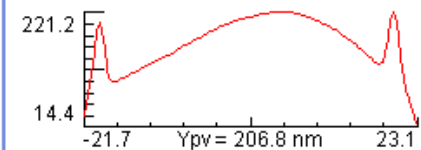
Coupe sur l'axe X

Fermer Copier Options Sauver



Coupe sur l'axe Y

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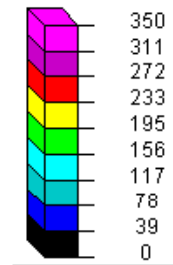
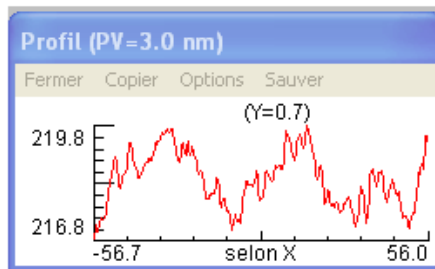
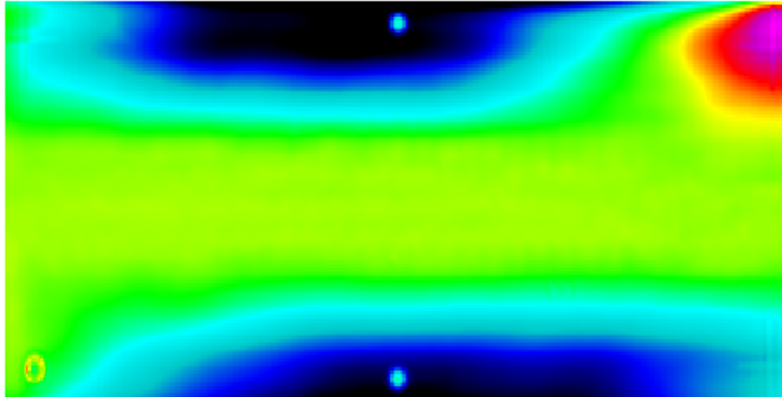


After surface correction (LMA)

Results:

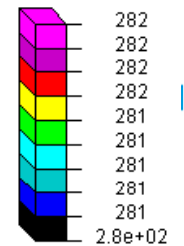
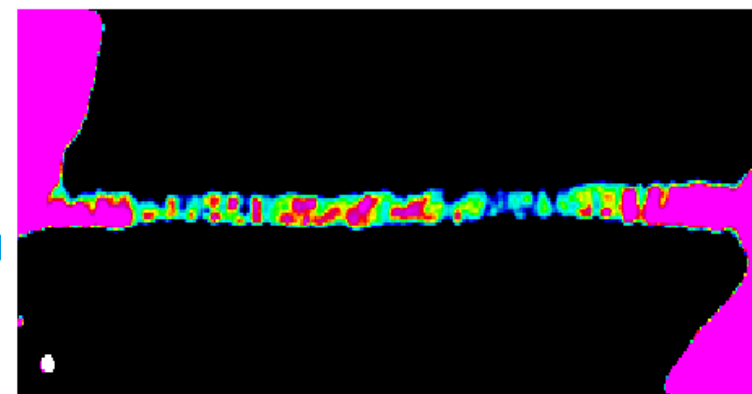
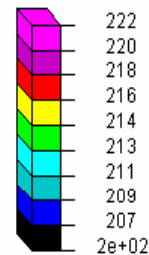
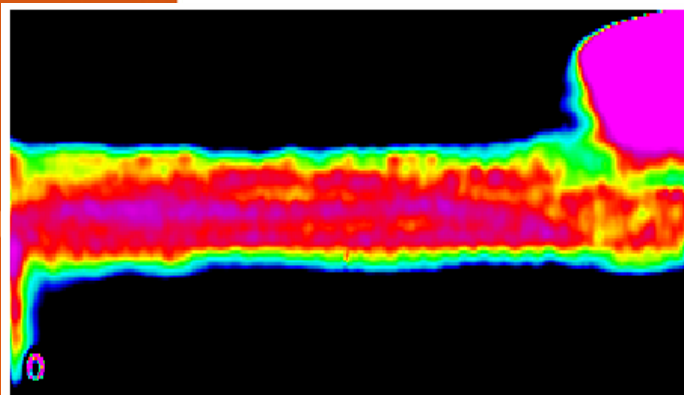
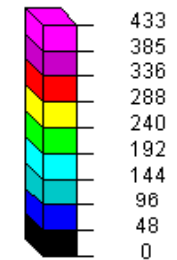
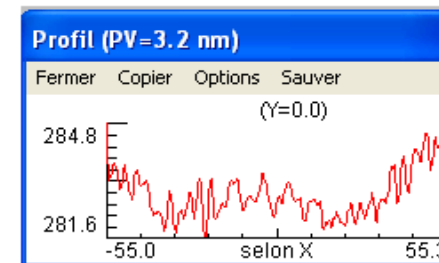
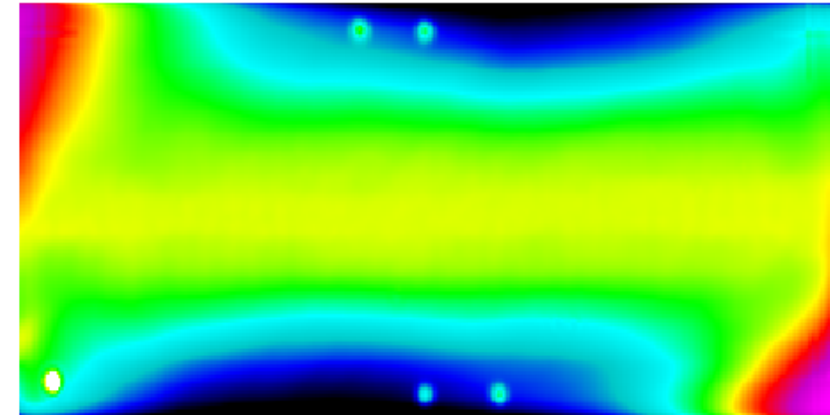
Substrat A

Shape error P to V: 3 nm



Substrat B

Shape error P to V: 3,2 nm

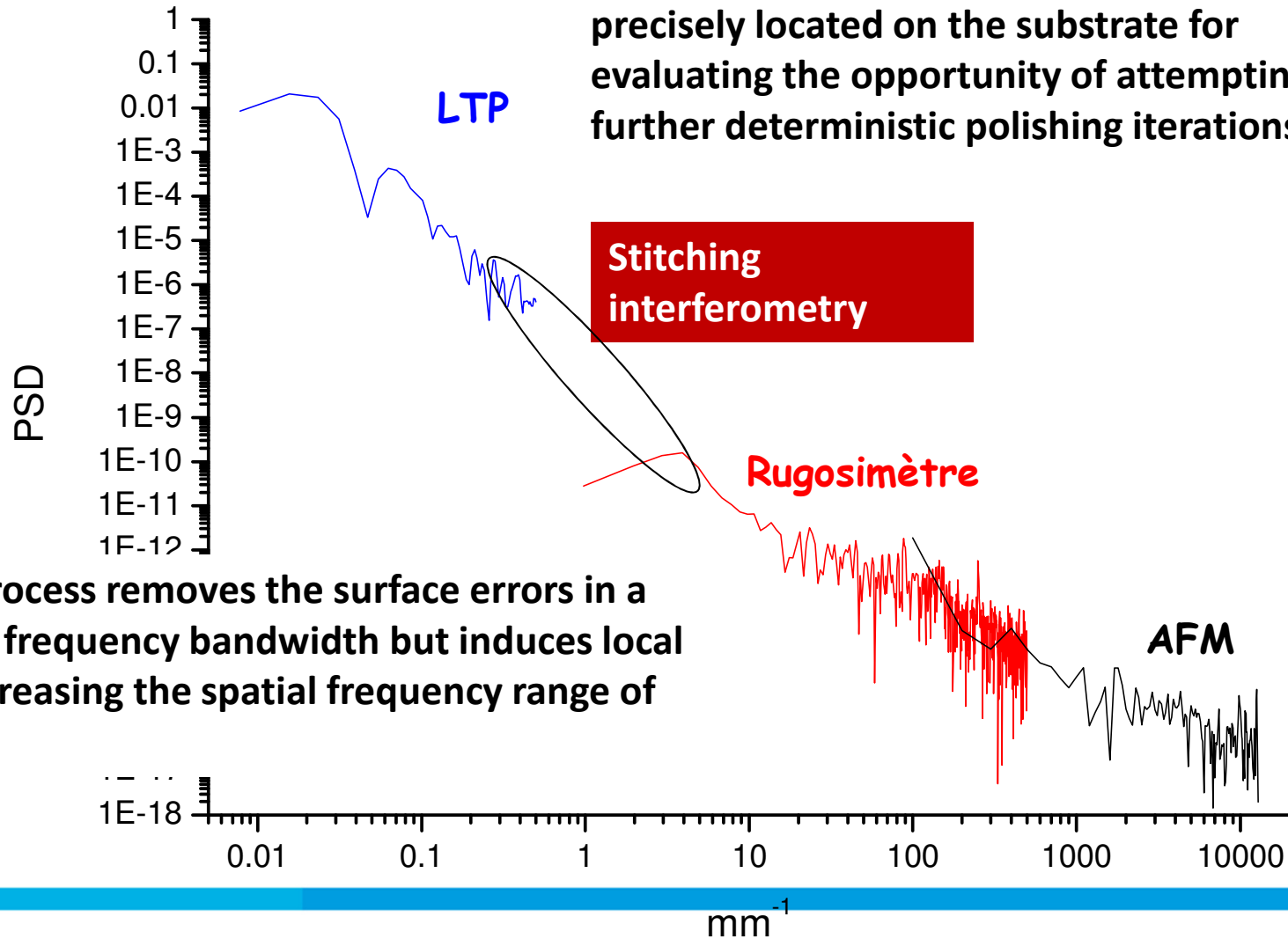




Task 5: Mirror metrology developments

Aim: to develop optical metrology adapted to nanofocusing optics

The spatial frequency range from 0.5 to 20 1/mm was missing. The defects must be precisely located on the substrate for evaluating the opportunity of attempting a further deterministic polishing iterations.



Re-polishing process removes the surface errors in a desired spatial frequency bandwidth but induces local side effects increasing the spatial frequency range of defects.

Available instruments, methods in the framework of AXOC

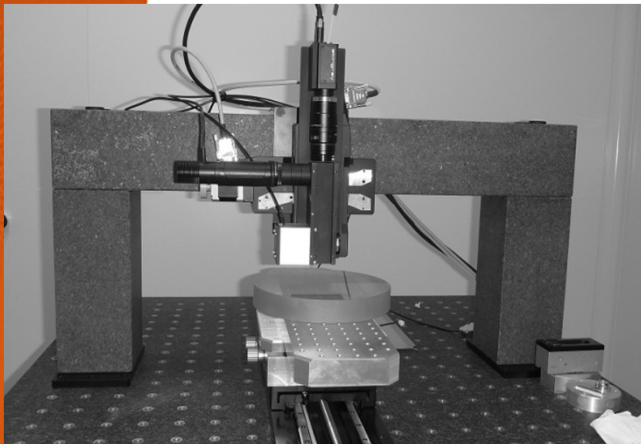
Stitching interferometry, under development at Soleil

Aim: to link a process of local surface **modification to surface shape measurements.**

Needed: sub-nanometer height accuracy and a lateral resolution below 1 mm.

Goal : ± 0.1 nm height accuracy; field of view up to 20 mm and, below $100 \mu\text{m}$ spatial resolution.

2nd prototype



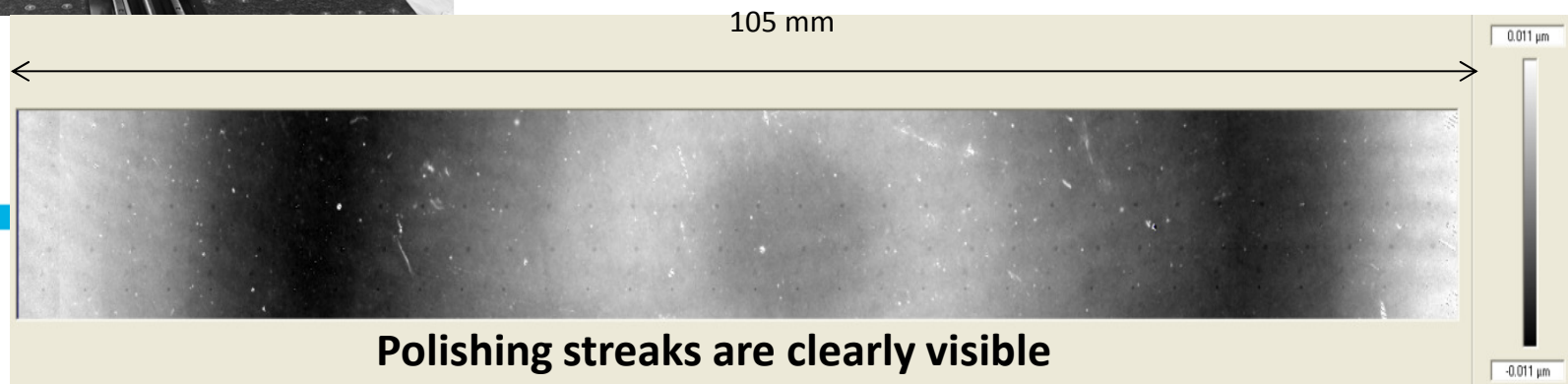
Results


Without any filtering, the short term repeatability is < 0.8 nm PV.

First stitching topography of a plane mirror stitching 20 individual images on 105 mm length.

Measurement step is 5 mm.


The slope error: $0.9 \mu\text{rad rms}$ (by LTP).





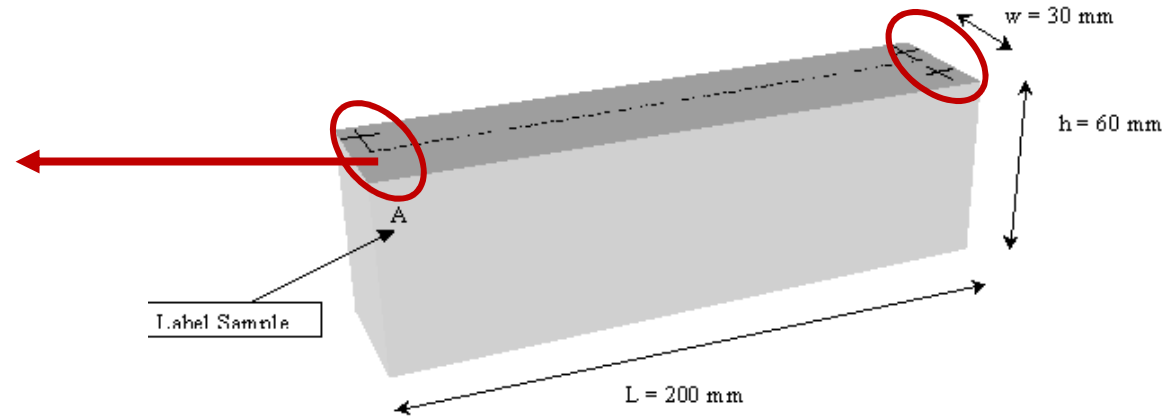
Muriel Thomasset, et al., **A new Phase-shift Microscope Designed for High Accuracy Stitching Interferometry**, Submitted for publication

F. Polack et al., **Determination and compensation of the “reference surface” from redundant sets of surface measurements**, Submitted for publication

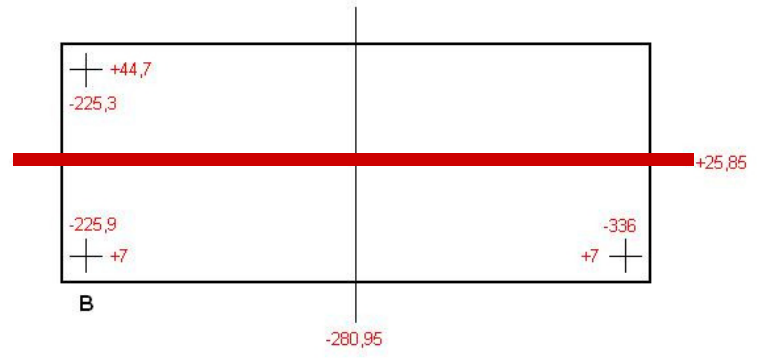
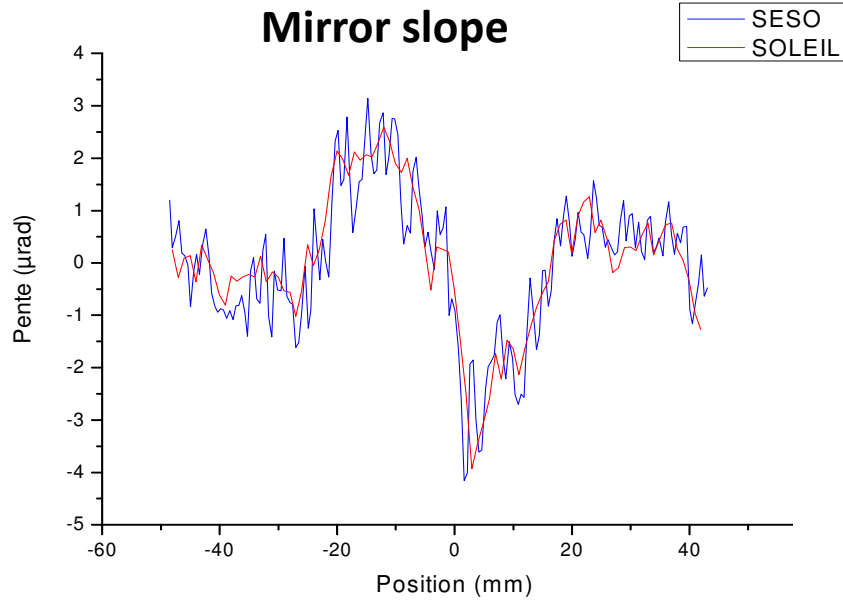


Intercomparison metrology SOLEIL-SESO-LMA: for each mirror

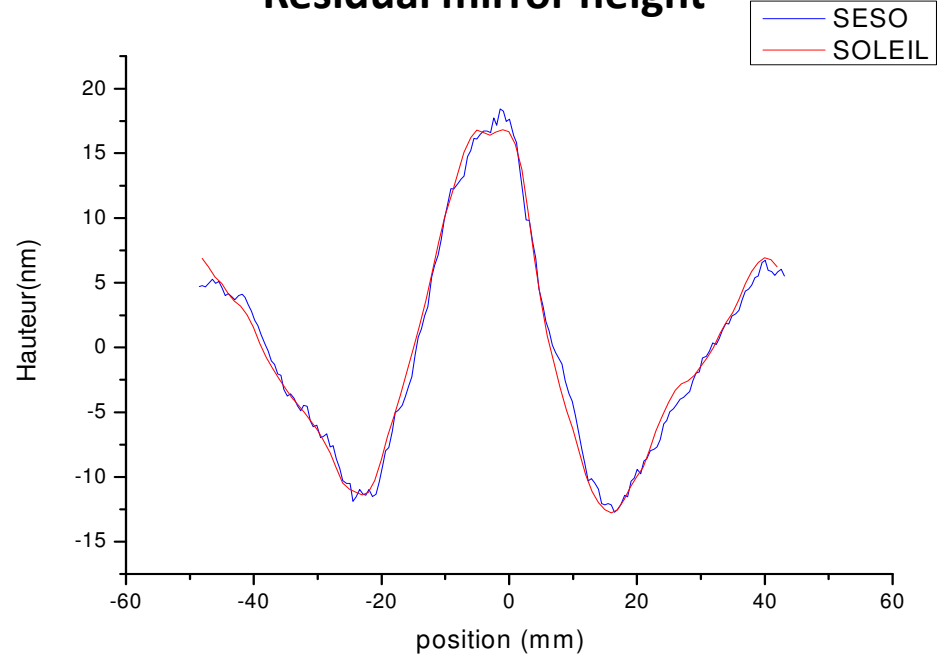
Fiducial markers:



Sensibility of mirror positioning: $20 \mu\text{m}$, repeatability: $< 50 \mu\text{m}$



Residual mirror height



Residual variation of the mirror slope and height after subtraction of the best sphere

SiO₂ substrate

